## Programmable Temperature Controller **MTC-P Series** User manual

Please read this manual carefully and keep this manual for future use

## General Specifications

- MTC-P series programmable temperature controller, 4 digits LED display, with bar graphic display, 0.2% accuracy, 0.1 resolution for thermocouple and Pt100 input signal, 0.001 resolution for analong input signal, auto/manual control bumpless transfer
- Maximum 4 different programs, each program with 8 segments, 4 program can be linked together as 1 program with 32 segments
- Maximum output power is configurable for each segment
- System time unit is switchable bewtee hour, minute and second
- Easy monitoring on current runing segment and program excution time period • The program can start from process value or from 0
- The program can be triggered or terminated by front key or start running automatically after power on and controller has the power failure restore function
- When program finished, controller can repeat the preset program again or stop operating completely
- Guaranteed soak function
- segment ending alarm», program ending alarm, program running alarm segment ending alarm delay function
- RS-485 optional, master/slave communication mode optional
- Please make sure the wiring is correct before power on, the wiring diagram is on the size of the controller for easy reference duing the wiring, make sure you are clear on the output type whether it is Relay, SSR drive or 4-20mA
- Controller can switch freely between thermocouple or RTD input signals for analog inputs, need to specify before order
- The factory default control action is OUT1 for reverse control(heating) customer can set OUT1 as direct control(cooling)
- Factory default control mode is P.I.D mode
- When I=0,d=0, the control mode set as time proportional mode, proportaional value is rSt1, control cycle is Cyt1, the output decrease when rSt1 decrease under heating mode the output increase when rSt1 decrease under cooling control mode

# 1: Dimensions



# 2: Ordering information



## **1:Size Information**

- 48mm(Width)\*48mm(Height) 48:
- 48mm(Width)\*96mm(Height) **49**:
- 72mm(Width)\*72mm(Height) 96mm(Width)\*96mm(Height) 72:
- 96: 94: 96mm(Width)\*48mm(Height)
- 2:Version Code
  - P. Programmable temperature controller

## also known as Ramp and soak controller

## 3:Output

R:	Relay	5:	0-5VDC
<b>V</b> :	SSR drive	<b>6</b> :	0-10VDC
D٠	4-20mA	7.	1-5VDC

2: 0-20mA

## 4: Alarm options

- 1 alarm 1:
- 2: 2 alarms
- 3: 3 alarms

## 5: Power supply

- 96. 85~265VAC
- 6:Re-transmission

N:	Without re-transmission
P42:	PV re-transmission as 4-20mA
P005:	PV re-transmission as 0-5VDC
P010:	PV re-transmission as 0-10VDC
S42:	SV re-transmission as 4-20mA
S005:	SV re-transmission as 0-5VDC
S010:	SV re-transmission as 0-10VDC

## 7:Communication

Without communication **N**:

K: RS-485 Modbus RTU

## 8: Auxiliary Power supply

- N: Without auxiliary power supply
- 24: 24VDC
- Remark: not all options are available at the same time. some of function share the same terminals, so various functions may create conflicts with each other, consult our sales team before order

# 3: Wiring diagram



program reset and PRO indicator went black out

### 4.3 Status when program ends



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Commnication address 1

SET

SET

To next page

SET

SET



rom previous page				
PV <b>PSEL</b> sv 0001	PSEL=1 Access to parameter menu for #1 program	PV <b>PSEL</b> sv 0002	PSEL=2 Access to parameter menu for #2 program	PV <b>PSEL</b> sv <b>0003</b> n
↓ SET PV <u>5'' ! !</u> SET	SV1.1 SV for #1 segment of #1 program	↓ SET P <sup>V</sup> <u>5''2. 1</u> SET	SV2.1 SV for #1 segment of #2 program	▶ SET ▶ <b>5 ' ' ' ' ' ' ' ' ' '</b>
ч <mark>Ег []</mark> ↓ set	Tr1.1 Time for #1 segment of #1 program 0.0-999.9 hours or minutes 0-9999 seconds		Tr2.1 Time for #1 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	
v <u>ol i i</u> ↓ set	Ot1.1 Maximum output ratio for #1 segment of #1 program 0.0-100.0%	P <sup>V</sup> <b><u>□ ⊢ ∂. /</u></b> ↓ SET	Ot2.1 Maximum output ratio for #1 segment of #2 program 0.0-100.0%	PV <u><b>o</b></u> <u><u>b</u><u></u><u>b</u><u></u><u>b</u><u></u><u>b</u><u></u><u>b</u><u></u><u>b</u><u></u><u>b</u><u></u><u></u></u>
У <u>5 1.2</u> _ set	SV1.2 SV for #2 segment of #1 program	PV <u>5''2.2</u> set	SV2.2 SV for #2 segment of #2 program	PV <u>5''3.2</u>
⊻ <u>Ег І</u> ́́́́ट] ⊥ set	Tr1.2 Time for #2 segment of #1 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u><b>E</b> - 2.2</u> SET	Tr2.2 Time for #2 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u><b>E</b> - 3.2</u>   SET
™ <u>ос 12</u>   set	0t1.2 Maximum output ratio for #2 segment of #1 program 0.0-100.0%	PV 0222	Ot2.2 Maximum output ratio for #2 segment of #2 program 0.0-100.0%	PV <u>0632</u>
сана страната и странат И страната и страната и И страната и страната и И страната и страната и И страната и	SV1.3 SV for #3 segment of #1 program	PV <u>5''2.3</u> SET	SV2.3 SV for #3 segment of #2 program	PV <u>5''33</u>
* * <u>Er 13</u>   set	Tr1.3 Time for #3 segment of #1 program 0.0-999.9 hours or minutes 0-9990 seconds	▼ <b><u>E</u><u></u> <u>E</u><u></u></b>	Tr2.3 Time for #3 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	• Р <sup>V</sup> <u>ЕгЗЭ</u>
™ <u>ос іЗ</u> ∣ <sub>set</sub>	Ot1.3 Maximum output ratio for #3 segment of #1 program 0.0-100.0%	PV 023	Ot2.3 Maximum output ratio for #3 segment of #2 program 0.0-100.0%	PV <b>0633</b>
• <sup>•</sup> <u>5'' !Ч</u>   set	SV1.4 SV for #4 segment of #1 program	▼ <b><u>SET</u></b>	SV2.4 SV for #4 segment of #2 program	PV <b>5''3''</b>
* <sup>v</sup> <u>Ег [Ч</u> set	Tr1.4 Time for #4 segment of #1 program 0.0-999.9 hours or minutes 0-9999 seconds	▼ <u> </u> <u> </u>	Tr2.4 Time for #4 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	• Р <sup>V</sup> <u>Е-<u>3</u>Ч set</u>
* <b>06 14</b> SET	Ot1.4 Maximum output ratio for #4 segment of #1 program 0.0-100.0%	▼ <b>062.4</b> SET	Ot2.4 Maximum output ratio for #4 segment of #2 program 0.0-100.0%	PV <u>0634</u> SET
* <u>5'' 15</u>   set	SV1.5 SV for #5 segment of #1 program	* [PV 5'2.5]   SET	SV2.5 SV for #5 segment of #2 program	* <sup>PV</sup> <u>5''35</u> set
™ <u>Er !5</u> set	Tr1.5 Time for #5 segment of #1 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u>Er2.5</u>	Tr2.5 Time for #5 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u><b>E</b> - 3.5</u> SET
<sup>ру</sup> <u>ос 15</u> 1 set	Ot1.5 Maximum output ratio for #5 segment of #1 program 0.0-100.0%	PV 0225	Ot2.5 Maximum output ratio for #5 segment of #2 program 0.0-100.0%	PV 0635
<sup>∨</sup> <u>5′′ (5</u> ∫ set	SV1.6 SV for #6 segment of #1 program	PV <u>5''2.5</u> set	SV2.6 SV for #6 segment of #2 program	PV <u>5''3.5</u> set
™ <u>Ег !Б</u>   set	Tr1.6 Time for #6 segment of #1 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u>Er 2.6</u>	Tr2.6 Time for #6 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u><b>E</b> - 3.5</u> SET
ν <u>οε 15</u>	Ot1.6 Maximum output ratio for #6 segment of #1 program 0.0-100.0%	PV 0225	Ot2.6 Maximum output ratio for #6 segment of #2 program 0.0-100.0%	PV 0638
Р <sup>у</sup> <u>5'' ! 7</u> _ set	SV1.7 SV for #7 segment of #1 program	PV <u>512.7</u> set	SV2.7 SV for #7 segment of #2 program	PV <b>5''3.7</b> SET
Р <sup>V</sup> <u>Ег []</u> _ set	Tr1.7 Time for #7 segment of #1 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u>E-2.7</u> J SET	Tr2.7 Time for #7 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u><b>E</b> - 3.7</u> J SET
<sup>р∨</sup> <u>ос 17</u> ↓ set	Ot1.7 Maximum output ratio for #7 segment of #1 program 0.0-100.0%	PV 02.7	Ot2.7 Maximum output ratio for #7 segment of #2 program 0.0-100.0%	PV 0237
<sup>™</sup> <u>5′′′8</u> ↓ set	SV1.8 SV for #8 segment of #1 program	PV <b>52.8</b>	SV2.8 SV for #8 segment of #2 program	PV <b>5''3.8</b>
, ™ <u>Er 18</u> ↓ set	Tr1.8 Time for #8 segment of #1 program 0.0-9999.9 hours or minutes 0-9999 seconds	P <sup>V</sup> <u><i>E</i> − 2.8</u>	Tr2.8 Time for #8 segment of #2 program 0.0-999.9 hours or minutes 0-9999 seconds	PV <u>∠ - 3.8</u> ↓ SET
v <u> ob</u> <u> b</u> <u> set</u>	Ot1.8 Maximum output ratio for #8 segment of #1 program 0.0-100.0%	P <sup>V</sup> <u><i>ob</i></u> 2.8 ↓ set	Ot2.8 Maximum output ratio for #8 segment of #2 program 0.0-100.0%	PV <u>o£ 3.8</u> ↓ set
•	PV/SV mode		PV/SV mode	PV <b>DC</b>



different programs can be linked together using PLNK parameter, linked program with 16,24, or 32 segments

## 6 2 Typical application

Suppose we need a program with 5 segments, using #1 program for the application, check below curve, the maximum output ratio restricted to 80% at segment 4 to avoid damage. system timing unit: hours SV Temperature 300 300 Dwell (2) Ramp 250 Segment 2 Ramp 3 Ramp Dwell 220 5 Segment 3 1 (4) Segment 5 Segment 4 Segment 1 Time 1 hour 0.5 hour 0.7 hour 1.5 hour 0.3 hour How to create a program like above figure ΡV PV/SV mode sv Press SET until you see PLCK ΡV ΡV ΡV ΡV SET SET SET sv sv sv sv 30 :: SET PLCK=2 to access to program SET PLNK=1 to use the #1 program for SET PSEL=1 goes to parameter menu Set the SV for #1 segment at 300C configuration menu the applicatio for #1 program SET ΡV ΡV P٧ P١ SET SET SET 10 SV sv sv SV Set the ramp time for #1 segment at 1 hour Maximum output for #1 segment is 100% Set the SV for #2 segm Dwell time for #2 segment at 0.5 hour SET ΡV ΡV ΡV ΡV SET SET SET sv 1000 sv sv sv 1000 : : 1 Set the SV for #3 segment at 220 C Ramp time for #3 segment is 0.7 hour Maximum output for #3 segment is 100% Maximum output for #2 segment is 100% SET ΡV ΡV ΡV P٧ SET SET SET sv SV sv sv Set the SV for #4 segment at 220 C Maximum output for #4 segment is 80% Set the SV for #5 segment at 250 C Dwell time for #4 segment at 1.5 hour SET P٧ ΡV ΡV 15 P١ 亡 SET SET SET П 888.8 888.8 SV SV 188.8 SV S٧ Ramp time for #5 segment is 0.3 hour Maximum output for #5 segment is 100% SET SV as any random value for #6 segment SET any random value for time of #6 segment SET Press SET key for 3 seconds or light press A/M key to save ΡV ΡV the configuration and exit from m i i Ti the programing menu 0.0 SV SV PV/SV mode

SET maximum output as 0.0% for #6 segment

#### 63 Program automatically terminated

SET the maximum output menu as 0.0% at certain segment if a program less than 8 segments and program ending when it comes to the last segment. in above case, the program only have 5 segments, then set the maximum output for #6 segment as 0.0%, program ends after 5 segments.

#### Program automatically jumping 64

If a program needs to skip on certain segments, set the segment time as 0.0, when program runs to the segment where the time has been set as 0.0, it will go to next segment automatically, for example, in a program where we want to skip on segment 4, then SET the time for segment 4 as "0.0", then program automatically goes to segment 5 from segment 3.

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## 6 2 Programming level 2

Refer to right figure, press SET key for 3 seconds to enter into programming level 2, below parameter shows one by one on the fixed sequence

Parameter Notation	Parameter description	Range	Default value	Remark
P /	Proportional band for out1	0 0 ~200 0	20 0	Proportional band for output 1(SEP P=3.0 for analog input signal) unit is degree, when P1=0, controller works as ON/OFF controller
1	Integral time for out 1	0-3600 Sec	210	Integral time for output 1, when I1=0, integral action disabled integral action gets more sensitive when I1 gets bigger, but fluctation is more expected
d /	Derivative time for out 1	0-3600 Sec	30	Derivative time for out 1, when d1=0, the derivative action disabled derivative action gets more sensitive when d1gets bigger, but fluctation is more expected
REGL	Auto tuning offset value(AtVL)	0-199C	0	Set ATVL to prevent overshoot occurred during autotuning process.
EYE I	Control cycle time for out 1	0 to 999 Sec	20	Control cycle time for out 1 Set as 20 S for relay output, 2 S for SSR drive output
HYS (	Control Hysteresis For out1	0 0 to 100 0	2 0	When P1=0.0, OUT1 is on/off control In heating application PV >SV OUT1 terminated PV-SV-HYS1 OUT1 activated In cooling application: PV-SV OUT1 activated PV-SV OUT1 terminated
r56 /	Proportional reset For out1	30 to 30	50	Proportional reset for overshoot protection only for out1 output.(Auto set after auto-tun ing)
OPL	Output lower limit	0 0 to 100 0%	0 0	To set the output lower limit for out 1
OPH	Output higher limit	0 0 to 100 0%	100 0	To set the output higher limit for out 1
LEY	Access protection parameter	0000 0255	0	LCK-0000: all parameters are configurable LCK-0001: only SV value configurable LCK-0010: configurable on SV and parameters under programming level 1 LCK-0011: can not configure all parameters LCK-0101: all parameters are configurable, accessible to programming level 4

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## 6 3 Programming level 3

6 3 1 How to access to programming level 3

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Parameter	Parameter	Range	Default	lt Remark					
	Input signal selection								
1111-1	Input signal L	בע	F!	Ęρ	11	12	Π		
	notation L /		F	<u> </u>			N	Wu3 Po25	
	Range 400.0 %	1300 °C 2	00.0.°C	400 °C	400.0.°C	000 °C	1200 °C	2000 °C	
	Trange 400 0 C	, 1300 C 3	000 0 1	000 C	4000 0	800 C	1300 C	2000 C	
	Input signal 5	E r	Ь .	RNY .	RN3 RI	72  <i>R</i> N	1  PE	1 PE2	
	Description S	T R	В	2 -10VDC	0 -10VDC	50mV 0 -20m	Pt100	) Pt100	
	Range 1600 °C	100 0 °C 1700 °C	1800 °C	4 -20mA	0 -20mA	0 2011	-199 9~ 20	0 0C -200~ 800°C	
	Remark 1: User Remark 2: Analo	can select the og input has to	rmocoup be speci	le or Pt ified bef	100 via fro ore order	ont key except 0-2	0mV and	0-50mV	
dP	Decimal point for analog input	0 1,2 3	0	0: No d 3: 3 dec	ecimal point cimal point	1: 1 decim only appl	nal point icable for a	2: 2 decimal point nalog input	
LSPL	SV lower limit	-1999 to 9999	0	Setting Or to de	value lower lir fine the lower	nit limit temperat	ure for Re-ti	ransmission function	
USPL	SV higher limit	-1999 to 9999	400	Setting Or to de	value higher li fine the highe	imit r limit tempera	iture for Re-	transmission function	
UN IE	Display unit	0 1,2	0	0: Ce	lcius	1: Fahren	heit 2	2: Without Unit	
P'_'05	PV Bias value	499 to 199	0 0	To con	npensate t	he measuri	ing error f	rom the sensors	
P'_'FE	Sampling rate	0 to 30	25	When value gets smaller, the response to the sensor is more sensitive but can expect some fluctuation, when value gets bigger, it will have reverse effects					
RNL I	Analog input lower limit display value	-199~9999	0	For example, the display value is ANL1 when input is 4mA for 4-20mA range					
RNH I	Analog input higher limit display value	-1999~9999	2000	For inpu	For example, the display value is ANH1 when input is 20mA for 4-20mA range				
RLd I	Alarm mode for #1 alarm	00 to 18	11	To def refer t	ine the ala o alarm mo	rm mode fo ode figure fo	r #1 alarn or alarm n	n node description	
RH (	Alarm hysteresis for #1 alarm	0 0 to 100 0	10		Alarm High a Low al	hysteresis v Iarm(lower s Iarm(higher s	alue for #1 ide hystere side hyster	alarm esis) esis)	
RLd2	Alarm mode for #2 alarm	00 to 18	10	To def refer t	ine the ala o alarm mo	rm mode fo ode figure fo	r #2 alarn or alarm n	n node description	
RH2	Alarm hysteresis for #2 alarm	0 0 to 100 0	10		Alarm High a Low al	hysteresis v Iarm(lower s Iarm(higher s	alue for #2 ide hystere side hyster	alarm esis) esis)	
RLd3	Alarm mode for #3 alarm	00 to 18	10	To def refer t	ine the ala o alarm mo	rm mode fo ode figure fo	r #3 alarn or alarm n	n node description	
RH3	Alarm hysteresis for #3 alarm	0 0 to 100 0	10		Alarm High a Low al	hysteresis v Iarm(lower s Iarm(higher s	alue for #3 ide hystere side hyster	alarm esis) esis)	
OUJ	Control action	0 or 1	0	0:Reverse control(heating) 1:Direct control(cooling)			ng) J)		
ALE	ALt Program ending alarm delay time	0 <del>9</del> 999 Seconds	0	O When value=0, the alarm output right after program end Other value from 1-9999 seconds Program end alarm output delay certain (from 1-9999 seconds) then output				after program end 9 seconds) then output	
ūR iE	Wait	0 0 100 0 Celcius		0:Disab Other va	le program ho alue: temperal	lding function ture range to a	ctive the pro	gram holding function	
PUNE	PUNt System time units	012	0	0: Ho 1: Mir 2: Se	ur (0.0~99 nutes(0.0~ cond(0-99	9.9 Hour) 999.9 Min 99 Second	utes) Is)		

Parameter Notation	Parameter description	Range	Default value	Remark
PrF	PrF Temperature where the program starts to run	0 ,1	1	0: Program starts to run from 0 1: Program starts to run from process value
	Communication address	0 427	1	To configure the address of controller in communication mode
6RUJ	Communication rate	0123	2	bAUd=0 Rate=2.4K bAUd=2 Rate=9.6K bAUd=1 Rate=4.8K bAUd=3 Rate=19.2K

## \* Atlarm mode(ALd=00~18)

10: No alarm output 11: Deviation high alarm 12: Deviation low alarm

13: Deviation high/low alarm
14: Deviation band alarm
15: Process high alarm 16: Process low alarm

- 00: No alarm output 01: Deviation high alarm with alarm standby function 02: Deviation low alarm with alarm standby function 03: Deviation high/low alarm with alarm standby function 04: Deviation band alarm with alarm standby function 05: Process high alarm with alarm standby function 06: Process low alarm with alarm standby function 07: Comment and inc. Journal alarm standby function
  - 07: Segment ending alarm

## 17: Program execution alarm 18:Program ending alarm 6 3 2 Alarm mode specification

Code	ALD	Specification(Example for alarm 1)									
Ν	10 or 00	No alarm									
		AL1 0 LOW SV AL1									
A	11	AL1<0 LOW SV+AL1 SV HIGH									
	10	AL1 0 LOW SV SV+AL1 HIGH									
D	12	AL1<0 Alarm ON AH1 Deviation low alarm									
с	13	Deviation high/low alarm Alarm ON AH1 HIGH									
D	14	Deviation band alarm Alarm ON LOW SV-AL12 SV SV+AL1									
н	15	Process high alarm Alarm ON LOW LOW AL1 HIGH									
J	16	Alarm ON AH1 <sup>4</sup> LOW AL1 HIGH									
F	01	AL1 0 LOW SV SV SV+AL1									
		AL1<0 LOW SV+AL1 SV HIGH									
F	02	AL1 0									
F	02	AL1<0 AL1<0 Alarm ON AH1 Deviation low alarm with hold action Alarm ON AH1 HIGH HIGH									
G	03	Deviation high/low alarm with hold action Alarm ON AH1 <sup>*</sup> : AH1 Alarm ON LOW SV-AL1 HIGH									
м	04	Deviation band alarm with hold action									

Code	ALd	Specification(Take alarm 1 as example)				
к	05	Process high alarm with hold action Alarm ON LOW AL1 HIGH				
L	06	Process low alarm with hold action       Alarm ON     AH1       LOW     AL1				
2	07	Segment ending alarm				
3	17	Program execution alarm				
4	18	Program ending alarm				

Remark: "Alarm standby" function means if the alarm condition meets while controller just power on the alarm will not output, when temperature goes out to the alarm range and falls back to alarm range again, the alarm will output Alarm mode apply to all three alarms, alarm 1, alarm 2 and alarm 3.

### 6.3.3 Various alarm for program control

Segment ending alarm: When ALd=07, the alarm is defined as segment ends alarm AL(AL1, AL2, Al3) value means when program comes to the certain segment, the alarm will output

For example, When ALd1=07, AL1=2(or 0.2), means when program finish segment 2. the alarm will go off and remind operator that the segment 2 is finished.

Program ending alarm, When ALd01=17, the alarm is defined as program ends alarm, When program ends, the alarm will go off.

Program execution alarm, When ALd01=18, the alarm will go off when program starts

### 6 4 Programming level 4

6 4 1 How to access to programming level 4



- Follow instruction in 6.2 to goes to programming level 2, change LCK value to 0201 then press SET key for 3 seconds to save the change
- 2. Refer to image at right, Press SET and **4** at the same time for 3 seconds to goes to programming level 4, below parameter will display one by one

Parameter Notation	Parameter description	Range	Factory default	Remark
EonF	ConF Communication function setting	012	0	ConF =0: Turn off communication ConF =1: Turn on communication ConF =2: Turn on Master/Slave communication mode
E-SF	TrSF Re-transmission setting	0, 1	0	eq:trsF=0:Re-transmission on the process value trSF=1: Re-transmission on the setting value
PErL	PCrL Master/Slave communication mode configuration	0, 1	1	PCrL=0: Define controller as slave controller PCrL=1: Define controller as master controller
ot 1	Ot1 Analog output configuration	0, 1	0	Ot1=0: Define analog output as re-transmission output $Ot1=1$ : Define analog output as PID control output
RUED	AUtO Auto/manual control configuration	0,1	0	AUTO =0 : Disable auto/manual switch AUTO =1 : Enable auto/manual switch
P-00	PrON How programs starts to run after power on and after power failure	0, 1, 2	0	PrON=0.         Program resets right after power on, press start key to active the program manually.           PrON=1.         Program starts to run at the point before power cut off (apply in power failure situation)           PrON=2.         Program resets right after power on then runs the program automatically
PrEP	PrEP Program repeat mode configuration	0, 1	0	PrEP =0: Program doesn't repeat after program ends PrEP =1: Program repeat from segment 1 after one complete circle

# 7: Panel discription

Manual control works only after the program starts to run

All controllers except 48mm\*48mm with auto/manual (A/M) transfer key

Example: Following is an example of manual setting to 70% output.

Auto control mode

MAN lamp is turns

off in Auto control

mode





Press A/M key for 3 seconds to manual setting mode. In manual setting mode, MAN lamp light up, The digit which flashing is settable. Pressing the UP key increase numerals, and pressing the DOWN key decrease numerals. Press SET key after set value to 70.0.

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Manual control mode

# 8 AUTO-TUNING



Master controller: the SV value for the auto-tuning process is the SV for the first segment

Slave controller: the auto-tuning for the slave controller must be activated after the master controller, the setting value is related to master controller

# 9 Master and Slave Communication Mode

- 9 1 Master controller: Act as master controller to control slave controller
- 9 2 Slave controller: controlled by master controller, the SV value was given by master controller

SV and Rate parameter for slave controller

SV for slave controller, SV=(Rate ÷ 9999) X SV of master controller



SV for master and slave controller



## 10 RS 485 Communication

- (1) Support Modbus-RTU protocol, support 03 read command, 06 and 10 write command
- (2) Communication mode: single-master Rs485 asynchronous serial communication baud rate: 2400, 4800,9600,19200(9600 baud rate is factory default value)
- (3)The maximum write command for the controller is 36 at once, maximum read command is 37 at once for the read command

# 11 Input Ranges

Input type			(	Code	Input type			C	Code	
K 1	0 0 to 2	2000 0	2 2	D2		0.0	to 50.0 °C	Р	06	
K I	00 to 4	400 0 °C	2 2	D4	Pt1	0.0	to 100.0 °C	Р	07	
	0 to 4	400 ° <b>(</b>	C K	A4	(Pt100)	0.0	to 200.0 °C	Р	08	
K2	o to é	500 °C	C K	A6	(******)	-50.0	to 100.0 °C	P	13	
	0 to 1	1300 °C	CK	B3		-199.9	9 to +200.0 C	P	02	
F1	00 to 2	200 0 °C	3 3	D2		0	to 100 C	D	A1	
L 1	00 to 3	3000 °(	3	D3		0	to 200 C	D	A2	
	0 to 2	200 °C	СЕ	A2	Pt2	0	to 400 °C	D	A4	
F2	0 to 4	400 ° <b>(</b>	) E	A4	(Pt100)	0	to 800 °C	D	A8	
	0 to 6	500 °C	ΣE	A6		400	to 200 C		C2	
	00 to 3	300 0 °C	2 1	D3		200	to 400 C	D	C4	
JI	00 to 4	400 0 °C	2 1	D4		200	to 600 °C	D	C6	
	0 to 3	300 °(	7 J	A3		200	to 800 C		C8	
12	0 to 4	400 °	1 1	Α4	Input type			0	ode	
	0 to 8	300 °	<u> </u>	A8	AN1 0 to 20	)mV		V	01	
		300 0 °	<u>у т</u>	D2	AN2 0 to 50	DmV	-1999 to 9999	V	02	
Т		400 0 °		D3	AN3 0 to 5	/DC	-199 9to 999	, 🔽	03	
с .	00104	4000 C		D4	AN3 0 to 10	VDC		V	04	
×				80	AN4 1 to 5	/DC	-19 99to 99 9	) V	08	
R	U to 1	1/00 0		B/	AN4 2 to 10	DVDC	1 00010 0 000	, 🔽	09	
B	200 to 1	<u>1800</u>		B8	AN4 4 to 20	)mA	-1 333[0 3 33	' A	03	
N	0 to 1	<u>1300</u>		B3	AN3 0 to 20	)mA		A	02	
Wu3_Re25	600 to 2	2000 (	) W	BO	AN3 0 to 10	DmA		A	01	

Remark: when input signal is S thermocouple, the accuracy is not guaranteed at range 0-100 celcius

1: User can select thermocouple and Pt100 using front key

2: Analog input signal has to be specified before order expect 0-20mA and 0-50mA

\*\*In manual control mode ,press A/M key for 3 seconds to auto control mode. \*\*Power-on Manual function can be selected. Pko in level2 for initial output value \*\*A/M key can also be used for SAVE and EXIT key.